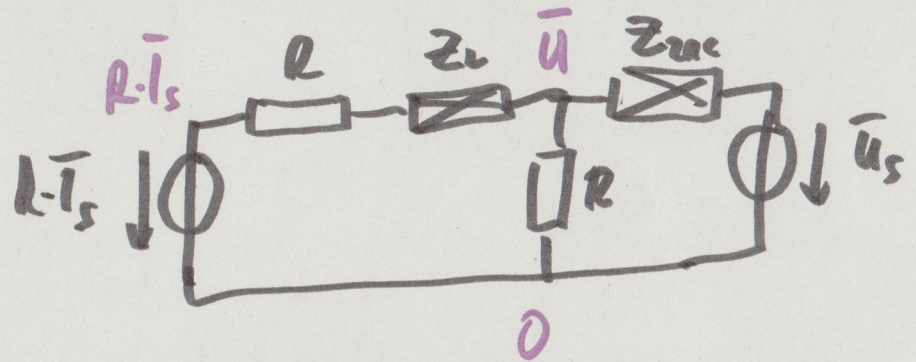
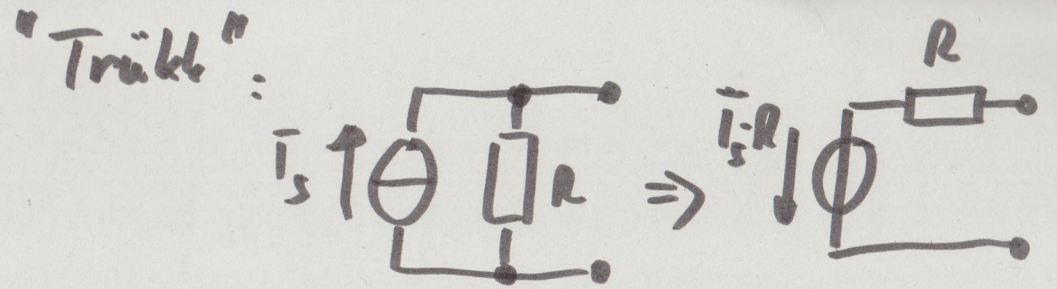


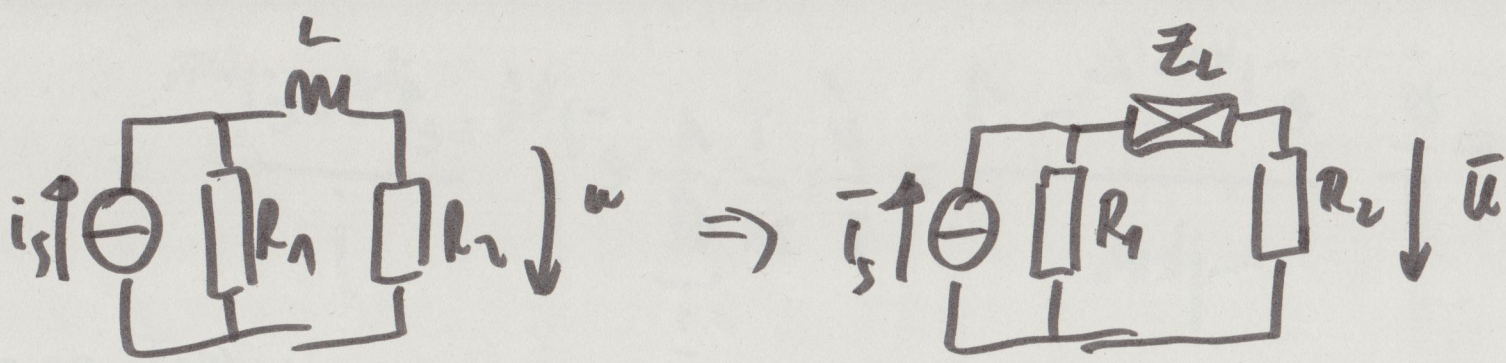
$$\bar{u} = (j\omega)^2 GLA U_s + j\omega(R^2 C U_s +$$



$$\frac{\bar{u} - \bar{i}_s R}{R + z_L} + \frac{\bar{u}}{R} + \frac{\bar{u} - \bar{u}_s}{2R + z_C} = 0$$

$$\bar{u} = \frac{\bar{i}_s \frac{R}{R + z_L} + \frac{\bar{u}_s}{2R + z_C}}{\frac{1}{R} + \frac{1}{R + z_L} + \frac{1}{2R + z_C}}$$





$$\bar{i}_s \rightarrow \bar{i}_s(j\omega)$$

$$\bar{u} = \frac{R_2}{R_2 + Z_L} \cdot \bar{i}_s \cdot R_1 \times (R_2 + Z_L) = \bar{i}_s \cdot \frac{R_1 \cdot \cancel{(R_2 + Z_L)}}{R_1 + R_2 + Z_L} \cdot \frac{R_2}{\cancel{R_2 + Z_L}}$$

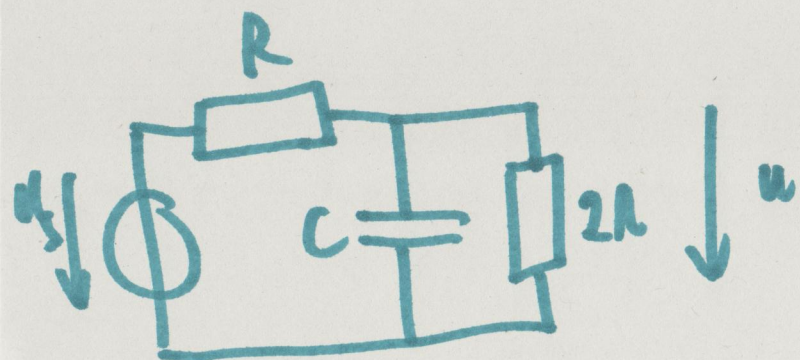
$$\bar{H} = \frac{\bar{u}}{\bar{i}_s} = \frac{R_1 R_2}{R_1 + R_2 + Z_L} = \frac{R_1 R_2}{R_1 + R_2 + j\omega L} = \frac{R_1 R_2}{L} \cdot \frac{1}{j\omega + \frac{R_1 + R_2}{R_1 R_2 L}}$$

$\underbrace{\frac{R_1 \times R_2}{L}}$   
 $L$

$$\bar{H}(j\omega) = A_0 \cdot \frac{1}{j\omega + \Omega}$$

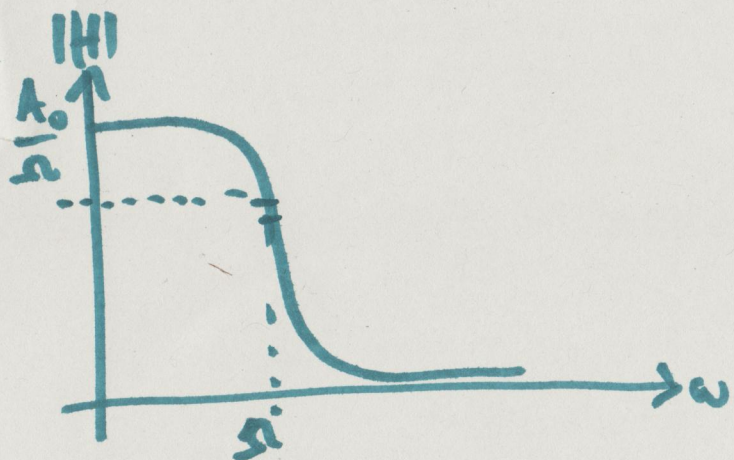
$$[A_0] = \frac{[A]/[L]}{1} \cdot [A] = [\omega] \cdot [A]$$





$$U(j\omega) = \frac{2R \times Z_C}{R + 2R \times Z_C} \cdot U_s(j\omega) =$$

$$= \frac{\frac{2R \cdot Z_C}{2R + Z_C}}{R + \frac{2R \cdot Z_C}{2R + Z_C}} U_s = \frac{2R \cdot Z_C}{2R \cdot Z_C + 2R^2 + R \cdot Z_C} U_s$$



$$\frac{U}{U_s} = \frac{2Z_C}{3Z_C + 2R} = \frac{\frac{2}{j\omega C}}{\frac{3}{j\omega C} + 2R} = \frac{2}{3 + 2j\omega CR} =$$

$$= \frac{2}{2CR} \cdot \frac{1}{j\omega + \frac{3}{2CR}} = \frac{1}{RC} \cdot \frac{1}{j\omega + \Omega}$$

$$\text{to } A_0 = 1/RC$$

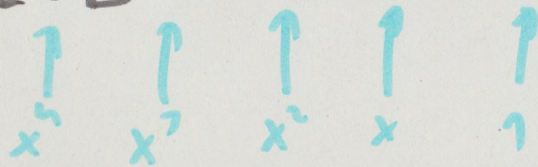
$$\Omega = \frac{3}{2RC}$$



polinom reprezentáció

$$5x^4 - 3x^3 + 9x - 10 \rightarrow \text{egyenlet}$$

$$s = [5 \quad -3 \quad 0 \quad 9 \quad -10]$$



polyval(s, 3)

$x=3$  helyettesítés  $\rightarrow 349$

polyval(s, [1, 2, 3])

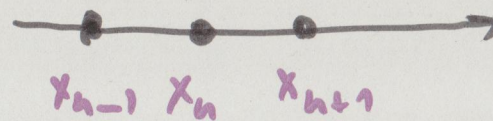
$x=1$   
 $x=2$   
 $x=3$

$\hookrightarrow [1 \quad 64 \quad 349]$

$x = 0: 0.1: 10;$

$y = \text{polyval}(s, x); \text{plot}(x, y, 'r-o');$

Lineáris távolsági pontok

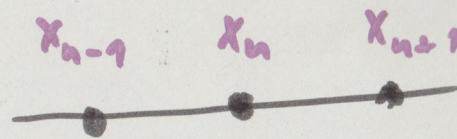


távolság állandó!

$$x_n - x_{n-1} = x_{n+1} - x_n$$

$$\Rightarrow x_n = \frac{x_{n+1} + x_{n-1}}{2}$$

Logaritvisszaeső egyenlő távolságú pontok



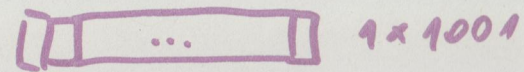
arány állandó!

$$\frac{x_n}{x_{n-1}} = \frac{x_{n+1}}{x_n} \rightarrow x_n = \sqrt{x_{n-1} \cdot x_{n+1}}$$



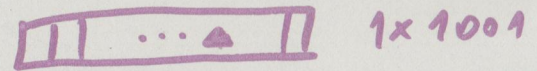
Polinom kifejezés ábrázolás

$om = 0:0.1:100;$



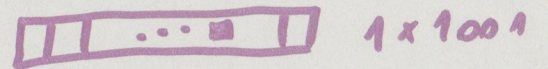
$$num = [3 \ 2 \ 1]$$

$\rightarrow polyval(num, j \times om)$



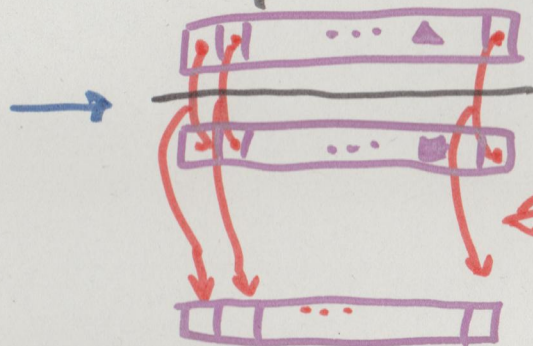
$$den = [1 \ -2 \ 3 \ 4]$$

$\rightarrow polyval(den, j \times om)$



elemenköti műveletvégzés (osztás)

$$\frac{3x^2 + 2x + 1}{x^3 - 2x^2 + 3x + 4}$$



$\rightarrow polyval(num, j \times om) ./ polyval(den, j \times om)$

olyan mint a for-ul végig bemenő

$n1 = polyval(num, j \times om);$

$d1 = polyval(den, j \times om);$

$p = zeros(size(n1));$

for id=1:length(n1)

end

$p(id) = n1(id) / d1(id);$



$$u_1(t) = [3 + 2 \cdot \cos(1t) + 4 \cdot \cos(2t - 0,5)] \text{ V}$$

$$R = 2 \text{ k}\Omega;$$

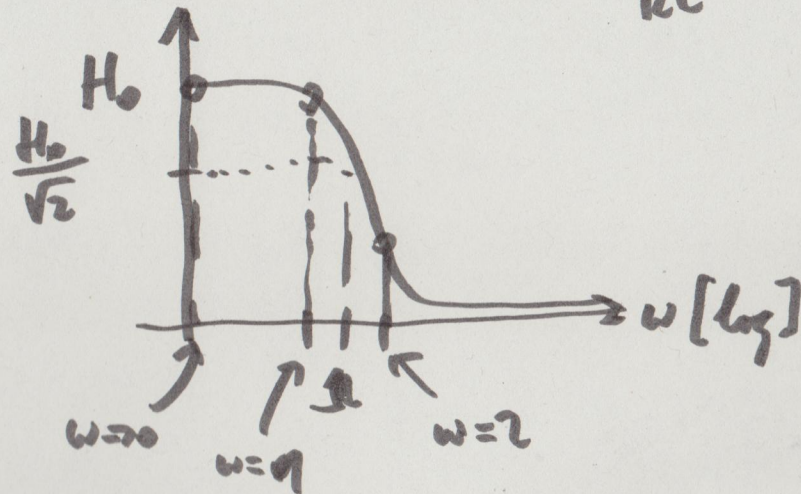
$$C = 0,4 \mu\text{F}$$

$$u_2(t) = ? \quad H(j\omega) = A_0 \cdot \frac{1}{j\omega + \Omega}$$

$$\frac{1}{RC} = 1,25 \frac{\text{Mrad}}{\text{s}}$$

$$A_0 = \frac{1}{RC} = 1,25$$

$$\Omega = \frac{3}{2RC} = 1,875$$

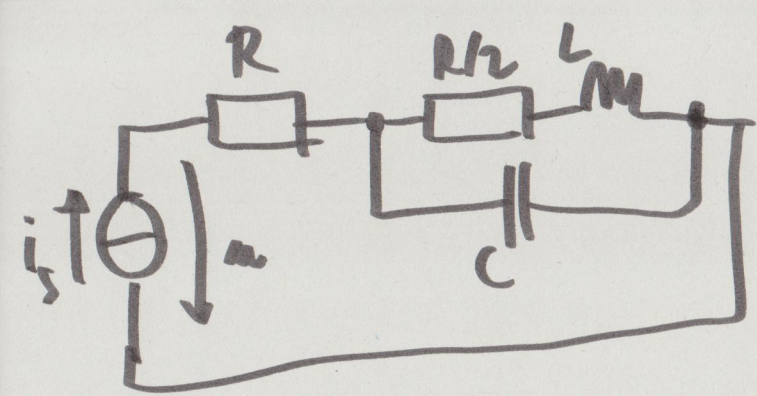


$\omega$	0	1	2
$\bar{u}_s$	3	2	$4e^{-j0,5}$
$\bar{H}$	$\frac{1,25}{1,875} = \frac{2}{3}$	$0,5883$ $\angle -0,49$	$0,4559$ $\angle -0,817$
$\bar{y}$	2	$1,1765$ $\angle -0,49$	$1,8238$ $\angle -1,317$

Teljes megoldás:

$$[2 + 1,1765 \cdot \cos(1t - 0,49) + 1,8238 \cdot \cos(2t - 1,317)] \text{ V}$$





$$u(j\omega) = \underline{I}(j\omega) \left\{ R + \frac{1}{j\omega C} \times \left( \frac{R}{2} + j\omega L \right) \right\} = \underline{I}(j\omega) \left\{ R + \frac{\frac{1}{j\omega C} \cdot \left( \frac{R}{2} + j\omega L \right)}{\frac{1}{j\omega C} + \frac{R}{2} + j\omega L} \right\}$$

$$= \underline{I}(j\omega) \cdot R + \frac{R + j\omega 2L}{2 + j\omega CR + (j\omega)^2 2LC} = \underline{I}(j\omega) \cdot \left\{ \frac{2R + j\omega \cdot CR^2 + (j\omega)^2 2CLR + R + j\omega 2L}{2 + j\omega CR + (j\omega)^2 2LC} \right\}$$

$$= \underline{I}(j\omega) \cdot \frac{(j\omega)^2 2CLR + j\omega(CR^2 + 2L) + 3R}{(j\omega)^2 2CL + j\omega CR + 2} = \underline{I}(j\omega) \underbrace{\frac{2CLR}{2CL}}_R \cdot \frac{(j\omega)^2 + j\omega \left( \frac{R}{2L} + \frac{1}{RC} \right) + \frac{3}{2LC}}{(j\omega)^2 + j\omega \frac{R}{2L} + \frac{1}{LC}}$$



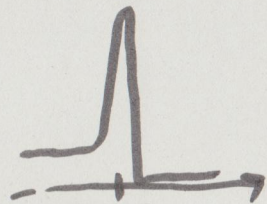
$$L = 1 \mu\text{H}$$

$\mu\text{H}, \text{pF}, \text{ms}, \text{Grad/s}, \text{k}\Omega$

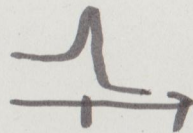
$$C = 0,9 \text{ pF}$$

$$R = 0,1 \text{ k}\Omega$$

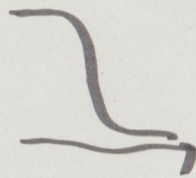
$$H(j\omega) = \frac{0,1 (j\omega)^2 + 1,1111 j\omega + 0,1667}{(j\omega)^2 + 0,05 j\omega + 1,1111}$$



$$R = 1 \text{ k}\Omega \quad \frac{(j\omega)^2 + 1,6111 j\omega + 1,6667}{(j\omega)^2 + 0,5 j\omega + 1,1111}$$



$$R = 10 \text{ k}\Omega \quad \frac{10(j\omega)^2 + 51,1111 j\omega + 16,667}{(j\omega)^2 + 5 j\omega + 1,1111}$$



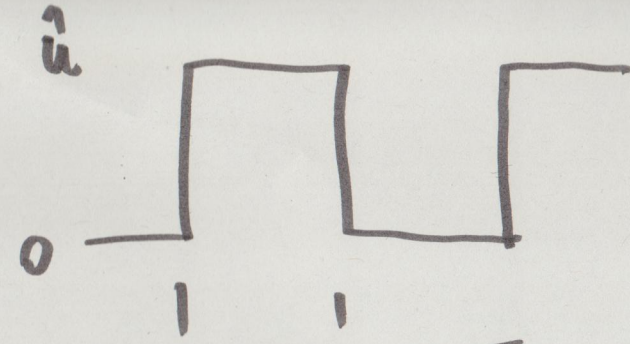


$$\bar{u}_b = \frac{1}{T} \int_0^T u(t) e^{-jk\omega t} dt =$$

$$= \frac{1}{T} \left[ \frac{e^{-jk\omega T/2} - 1}{-jk\omega} \right] \hat{u} =$$

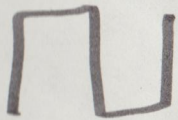
$$\frac{\hat{u}}{T} \cdot \frac{T}{2\pi} \cdot \frac{1}{k} \cdot \frac{e^{+jkx/2} - e^{-jkx/2}}{j}$$

$$2 \cdot \sin\left(\frac{kx}{2}\right)$$



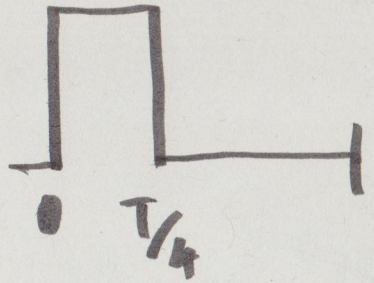
$$x = \frac{\omega_0 T}{2} =$$

$$= \frac{2\pi}{T} \cdot \frac{T}{2} = \pi$$



$\hat{u}_b$	0,5	0,6366	0,2122	0,1273	0,0905	0,0707
$\frac{\hat{u}}{T}$	-	-	-	-	-	-
$\rho_L$	-	$-\frac{T}{2}$	$-\frac{T}{2}$	$-\frac{T}{2}$	$-\frac{T}{2}$	$-\frac{T}{2}$
$\psi_{u_1}$	0	1	3	5	7	9





$$U_k = \frac{\hat{u}}{T} \frac{e^{-jk\omega_0 T/4} - 1}{-jk\omega_0} = \frac{\hat{u}}{T} \frac{T}{2\pi} \frac{1}{k} e^{-jk\frac{x}{2}} \frac{e^{jk\frac{x}{2}} - e^{-jk\frac{x}{2}}}{j} =$$

$$= \frac{\hat{u}}{\pi \cdot k} \cdot \sin(k\pi/4) e^{-jk\pi/4}$$

$$x = \frac{\omega_0 T}{4} = \frac{2\pi}{T} \cdot \frac{T}{4} = \frac{\pi}{2}$$

$\hat{U}_k$	0,25	0,4502	0,3183	0,1501	0	0,09	0,069	0,043	0
$\varphi_k$	-	$-\frac{\pi}{4}$	$-\frac{\pi}{2}$	$-\frac{3\pi}{4}$	-	$-\frac{\pi}{4}$	$-\frac{\pi}{2}$	$-\frac{3\pi}{4}$	-
$k$	0	1	2	3	4	5	6	7	8

